

Bremen



# Advanced Computer Graphics

## Striping / Stripping



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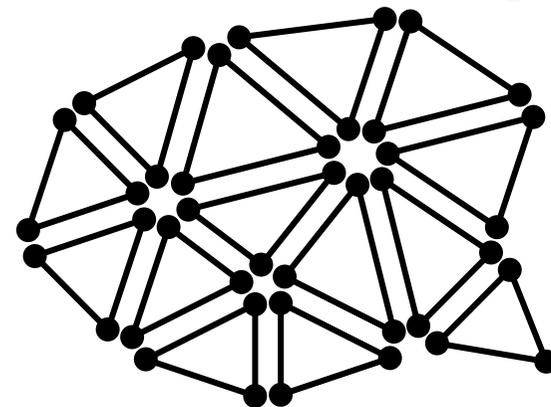
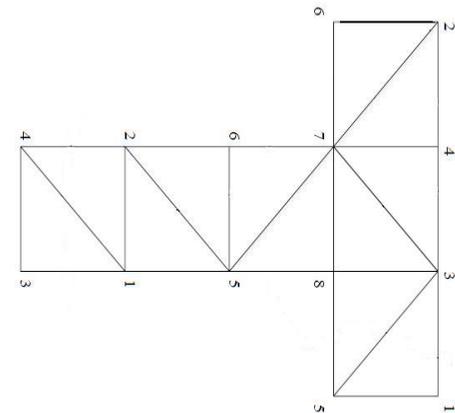
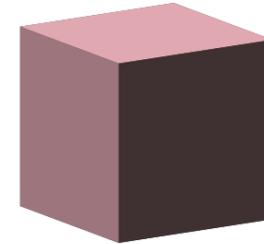
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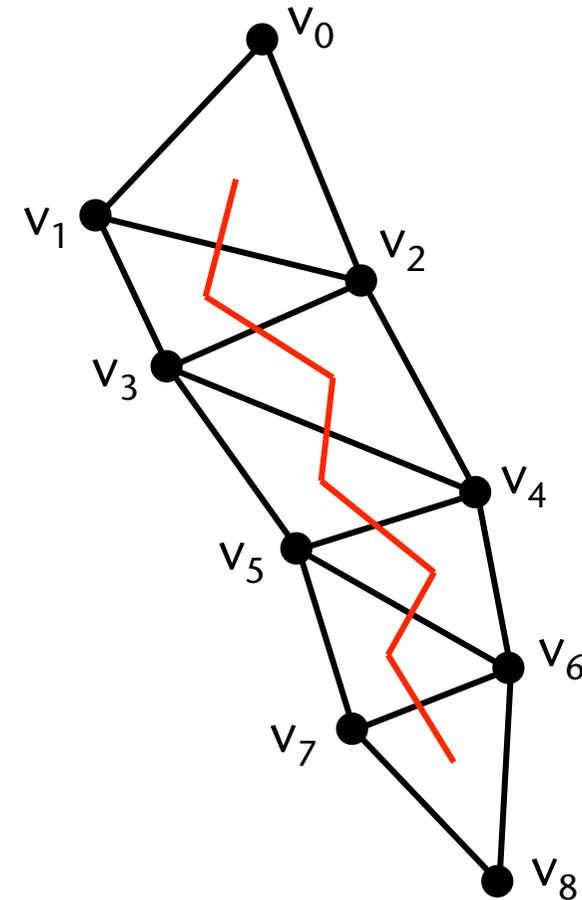
- In the following, consider only *triangle* meshes
- Naïve rendering:
  - $N$  triangles  $\rightarrow 3N$  vertices have to be sent to the graphics card
- Implementation in OpenGL:

```

glBegin( GL_TRIANGLES );
for ( unsigned int i = 0;
      i < n_tris; i++ )
{
    glVertex3fv( tri[i][0] );
    glVertex3fv( tri[i][1] );
    glVertex3fv( tri[i][2] );
}
glEnd();
    
```



- Graphics cards offer a special primitive: the **triangle strip**
- The idea:
  - The graphics card always "remembers" the 2 vertices which it received last
  - With each transmission of a new vertex, the graphics card forms a new triangle out of the new and the 2 "old" vertices
- Example:
  - 9 vertices  $\rightarrow$  7 triangles
- Advantage: factor 3 less vertex data need to be transmitted and processed!



Transmitted vertices:

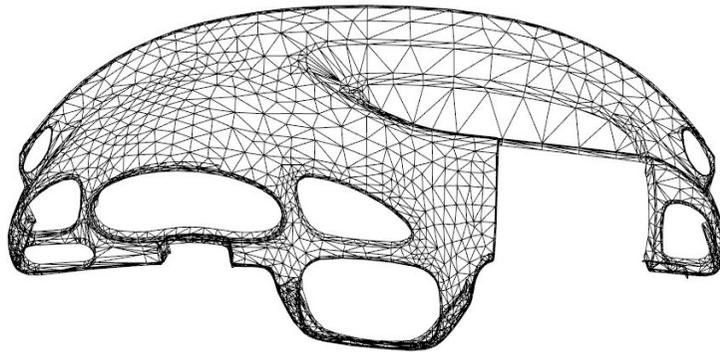
$V_0$   $V_1$   $V_2$   $V_3$   $V_4$   $V_5$   $V_6$   $V_7$   $V_8$

- Implementation in OpenGL:

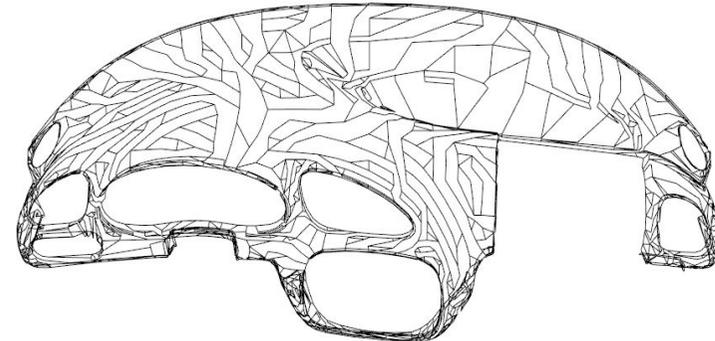
```
glBegin( GL_TRIANGLE_STRIP );  
for ( unsigned int j = 0; j < strip.n_verts; j ++ )  
    glVertex3fv( strip.v[j] );  
glEnd();
```



# Example of a "Striped" Object



4320 polygons  
12960 vertices

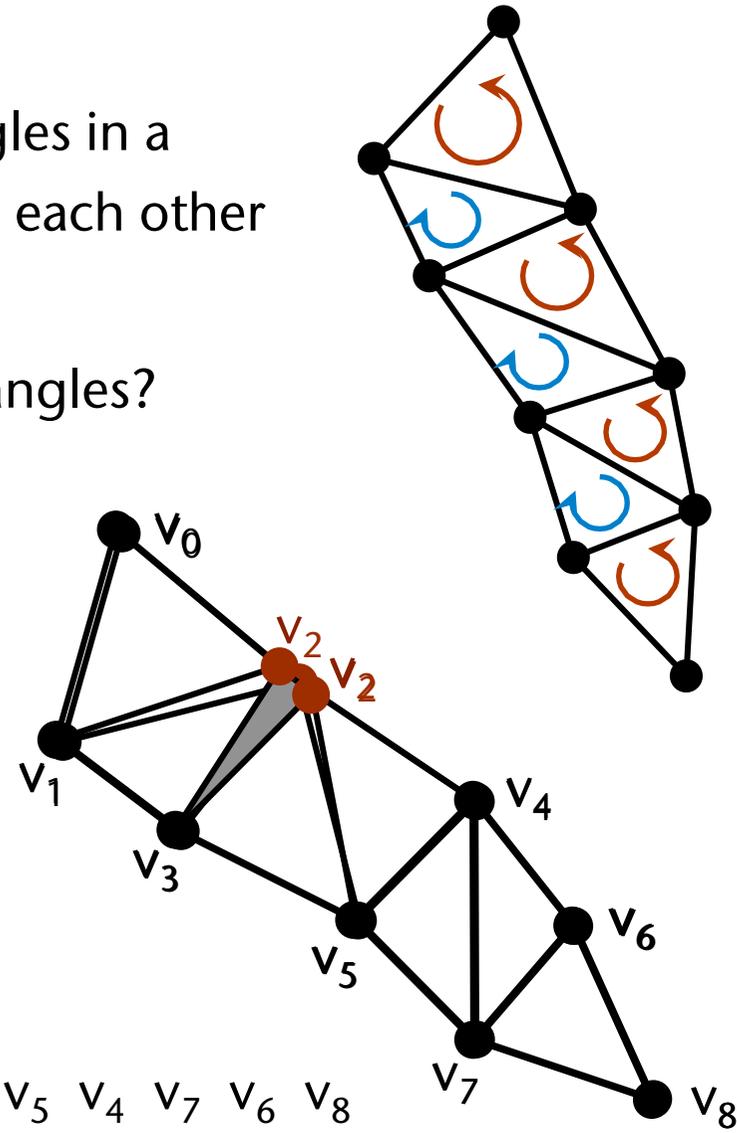


905 stripes  
6127 vertices

# Some Concepts

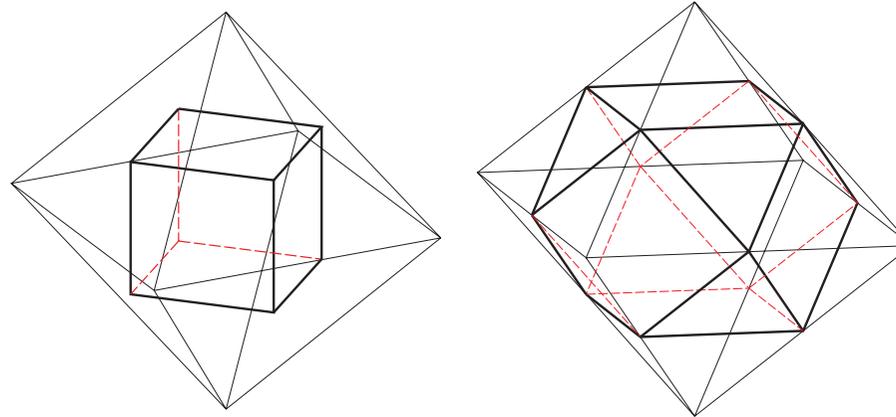
- Definition:
 

A **triangle strip** is a sequence of triangles in a mesh, so that two triangles following each other have a common edge.
- What about the orientation of the triangles?
- What can be done in such cases?
- Solution:
  - $V_2$  has to be transmitted twice
  - $V_2$  is called a **swap-vertex** – it creates a degenerated triangle



# A Geometric "Denksport-Aufgabe"

- Take an octahedron; determine the midpoints of its facets; connect the midpoints of adjacent facets → which polyhedron emerges?
- Take an octahedron; determine the midpoints of its edges; connect the midpoints of adjacent edges → which polyhedron emerges?
- Take a cube; connect the midpoints of adjacent facets → which polyhedron do you get?



# An NP-Complete Problem

- Questions:
  1. Is it possible to create a single strip out of each mesh?
  2. How can one (or more) strip(s) be created efficiently?

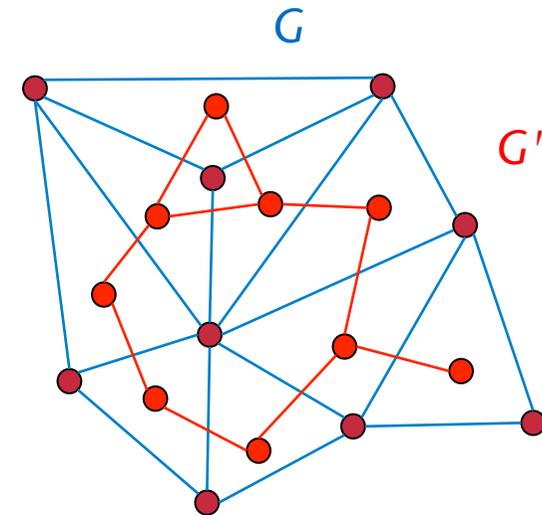
- Reduction of the problem:
  - Utilize the dual graph

- Definition of the **dual graph**:

Given a mesh / planar graph  $G = (V, E, F)$ .

The *dual graph*  $G' = (V', E', F')$  is derived

from  $G$  as follows: replace each facet of  $F$  by a node in  $V'$  and connect two nodes in  $V'$  by an edge, iff their original facets share a common edge (i.e., are adjacent).



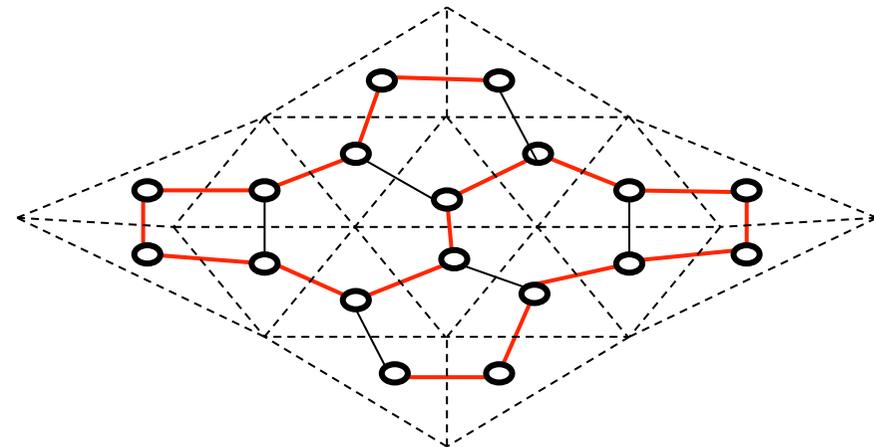
- Proposition:  
The problem "*decide for any triangle mesh  $M$ , whether it is possible to turn it into a single tri-strip*" is NP-complete!
  
- Proof, part 1:
  - To show: the verification of a "candidate" is in the class P
  - Let  $G'$  be the dual graph of the original mesh  $M$
  - We have:  $|E'| \in O(|V'|) = O(|F|)$
  - For  $E'$  create an adjacency matrix (using a hash table, this costs  $O(|E'|)$ )
  - Let a candidate strip be  $(v'_{i_1}, v'_{i_2}, v'_{i_3}, \dots, v'_{i_n})$ 
    - Each  $v'_{i_k}$  of  $G'$  corresponds to a triangle in  $M$
  - Check each pair  $(v'_{i_k}, v'_{i_{k+1}})$  of the candidate, whether it is contained in  $E'$

- Proof, part 2: reduction *from* a known NP-complete problem
  - The reduction from the know NP-complete onto our problem must be  $\in P$

- Definition **Hamilton path** :

Given a graph  $G$ . A *Hamilton path* is a path through  $G$ , so that each vertex is visited *exactly once*.

- Example :



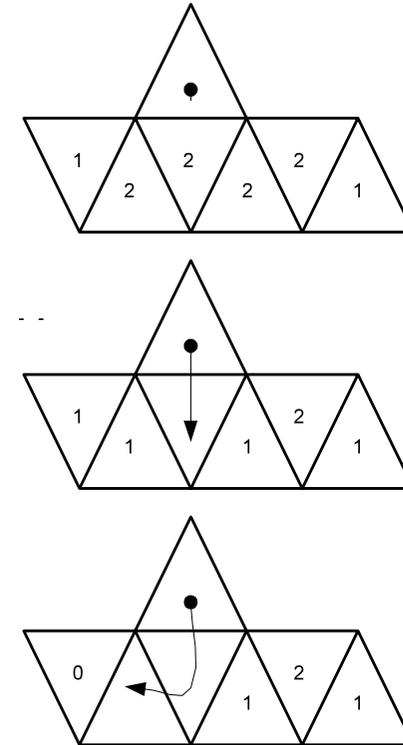
- Observations :

- A mesh/graph  $G$  has a single triangle strip iff the dual graph  $G'$  has a Hamilton path
- In case all facets within the (closed) mesh  $G$  are triangles, then all nodes in  $G'$  have degree 3 (= number of incident edges)

- Theorem from graph theory:  
The problem to decide, whether a given graph possesses a Hamilton path, is NP-complete.  
This is even the case, if all nodes within the graph have degree 3!
  
- Conclusion: "only" try to create as few strips as possible

- **Stripification** = stripping of a mesh into triangle strips
- Optimization task: only as few strips as possible, and overall as few "double" vertices / swap-vertices as possible
- Definitions:
  - Free triangle** := triangle that does not yet belong to a strip
  - Degree of a triangle** := number of *free* neighbor triangles

- The SGI-Algorithm [Akeley, 1990]:
  - Use a greedy strategy
  - The **local** criterion: go to the neighboring triangle with the smallest degree
  - Do look-ahead for tie-breaking

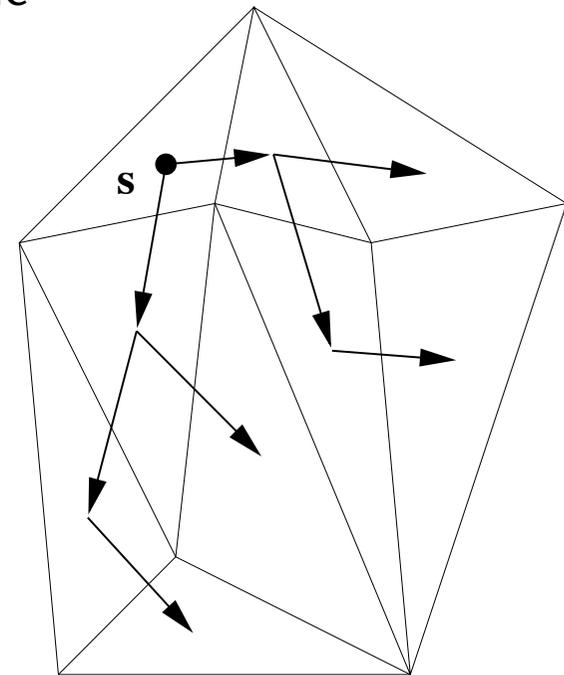


```

while ex. still free triangles:
    choose triangle with smallest degree
    start new strip with this triangle
    while last triangle in current strip has free neighbors:
        choose the neighbor with the lowest degree
        if tie:
            look one step ahead
        add triangle to current strip
    
```

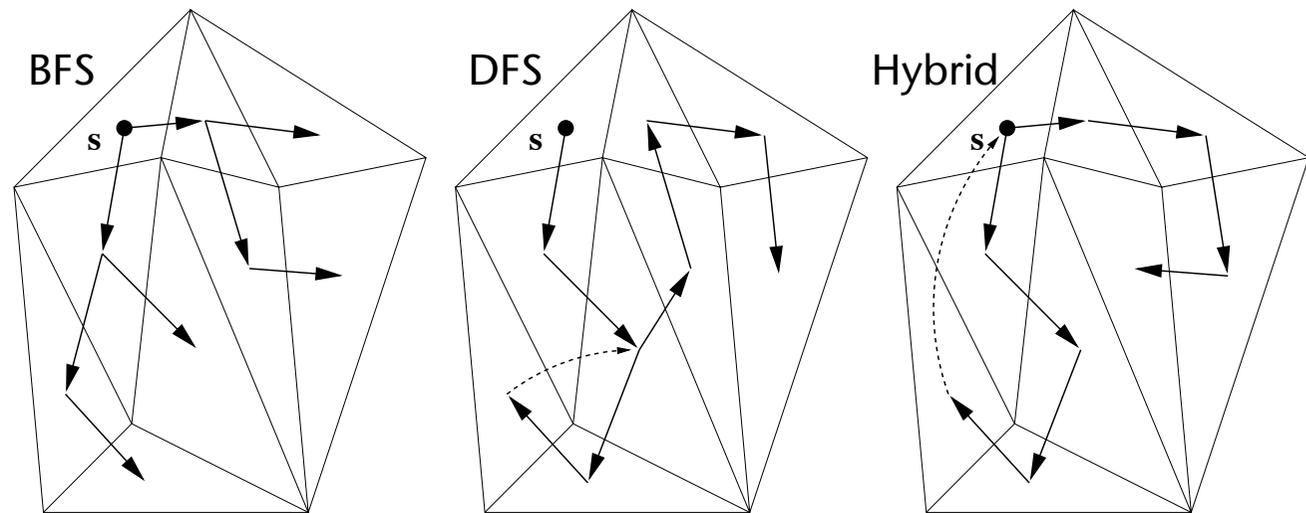
- The "Fast Triangle Strip Generator" (FTSG) [Xiang et al., 1999]:
  - One of the best algorithms (in the sense of rendering performance and the time of construction)
- Overview of the algorithm:
  1. Create a *spanning tree*  $T$  in the dual graph of the tri-mesh
  2. Partition  $T$  into as few paths as possible
  3. Possibly do post-processing: try to unite short strips
- Definition: spanning tree

- Regarding step 2 (partitioning the spanning tree  $T$ ):
  - Select a node  $v$  within  $T$  with degree 3 (has two children) and a level as deep as possible
  - The sub-tree with root  $v$  consists of a *single path* from the left to the right side; store this strip; delete the path from  $T$
  - Repeat, until no node with degree 3 remains
- Running time:  $O(n)$  (with the suitable data structures)

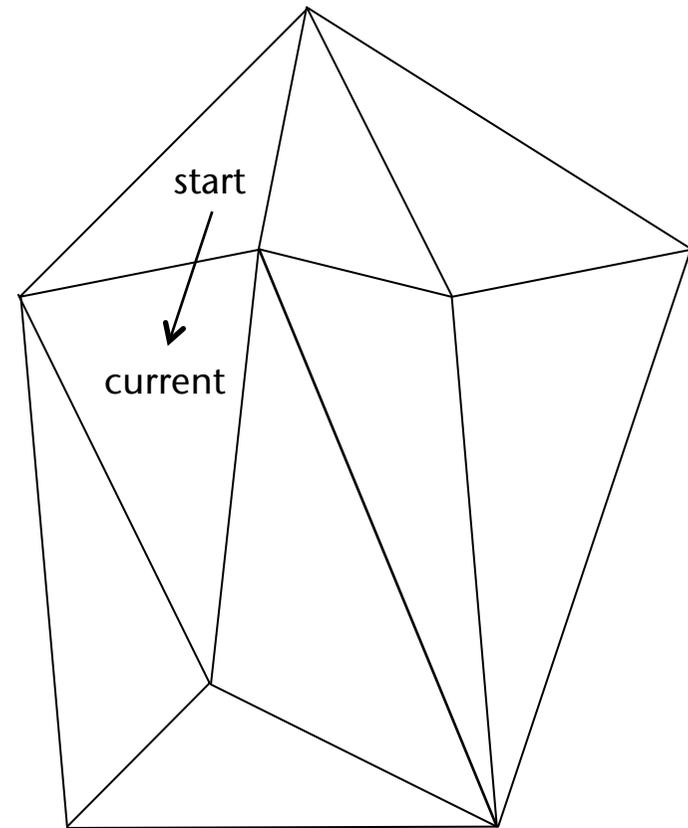


- Regarding step 1 (construction of the spanning tree  $T$ ):
  - Aim: try to construct a spanning tree with a minimal number of nodes that have degree 3 or higher = 2+ children
    - This is a consequence from step 2
  - Typical procedures for the construction of the spanning tree:
    - Breadth-first search (BFS) through the original graph
    - Depth-first search (DFS)

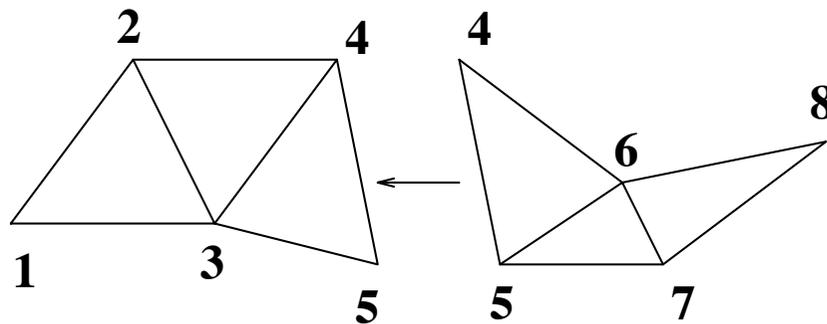
■ Practice shows:  
DFS yields the best results in this case



- Additional heuristics (since we need the spanning tree for special purposes):
  - Observation: during DFS through the graph, we have very often a free choice which neighboring node shall be visited next
  - Heuristic here: choose the neighboring triangle (= neighboring node in spanning tree  $T$ ) such that the current triangle and this neighboring triangle would not produce a *swap vertex*, if they were in a common triangle strip

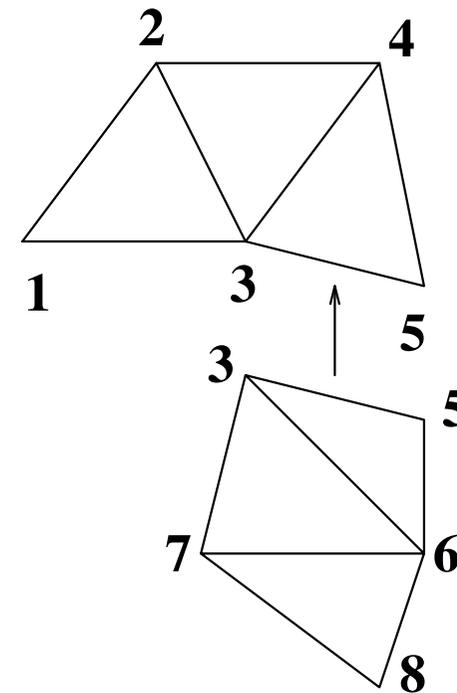


- Regarding step 3 (post-processing = concatenation of short strips):
  - The setup of strips (on the graphics card) costs more time than to send a vertex
  - Consequence: concatenate several short strips, even if that requires to insert a swap-vertex
  - Cases:



Good case

And 2 more cases ... (reduction by 1 vertex)



- Result: on average, ca. 1.23 vertices per triangle are sent during rendering
- Data structure: DCEL is a suitable candidate
- Observation: The performance depends very heavily on the DS!
  - With pre-implemented, generic DS (e.g., from a library) one is finished with the job quickly, but the performance is mediocre
  - With specially adapted, "hand-made" DS, the performance (hopefully!) is very good, but the implementation takes much longer

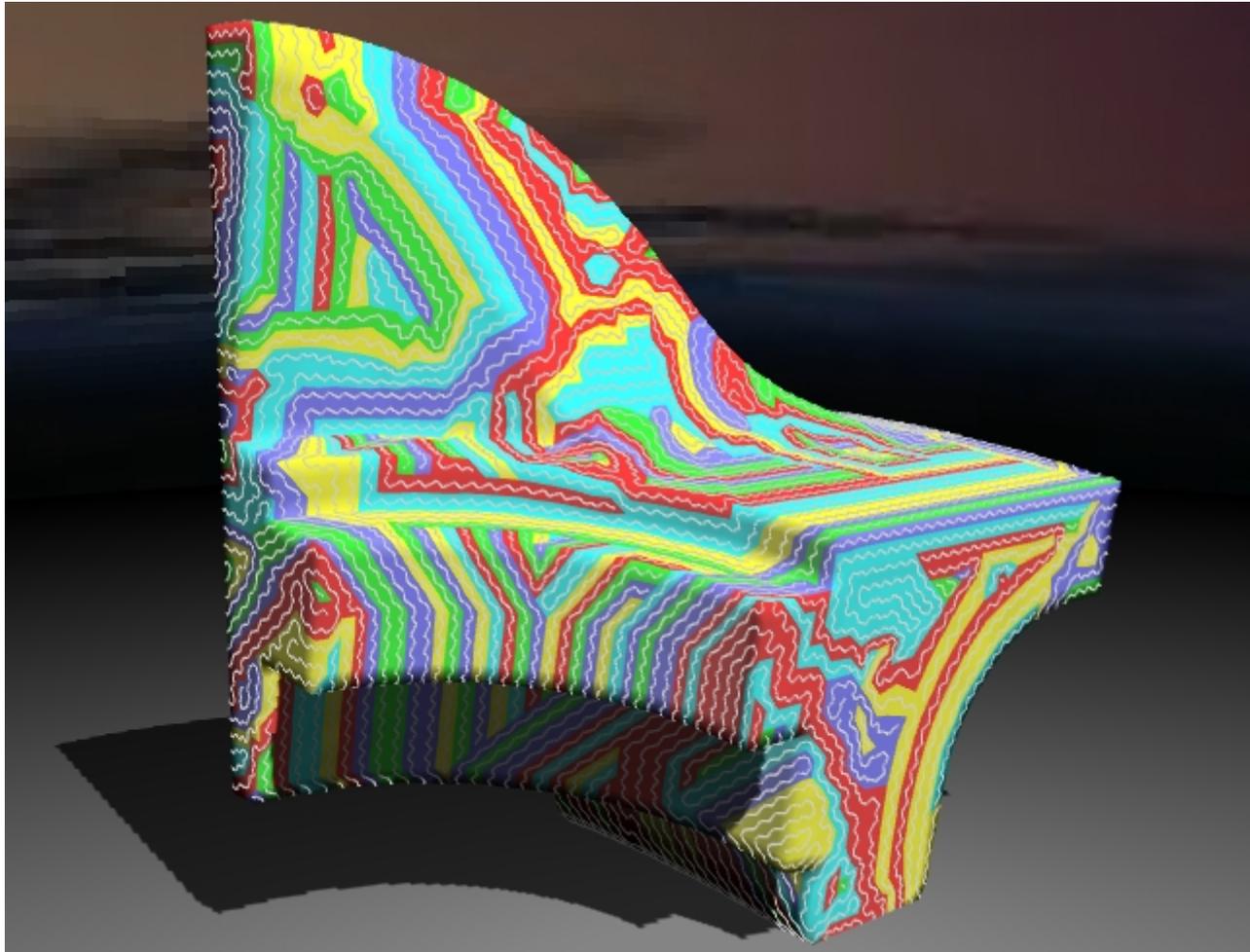
- A special data structure for stripification:
  - Utilize the fact that we only work with triangle meshes
  - Store all three incident edges directly with the triangles

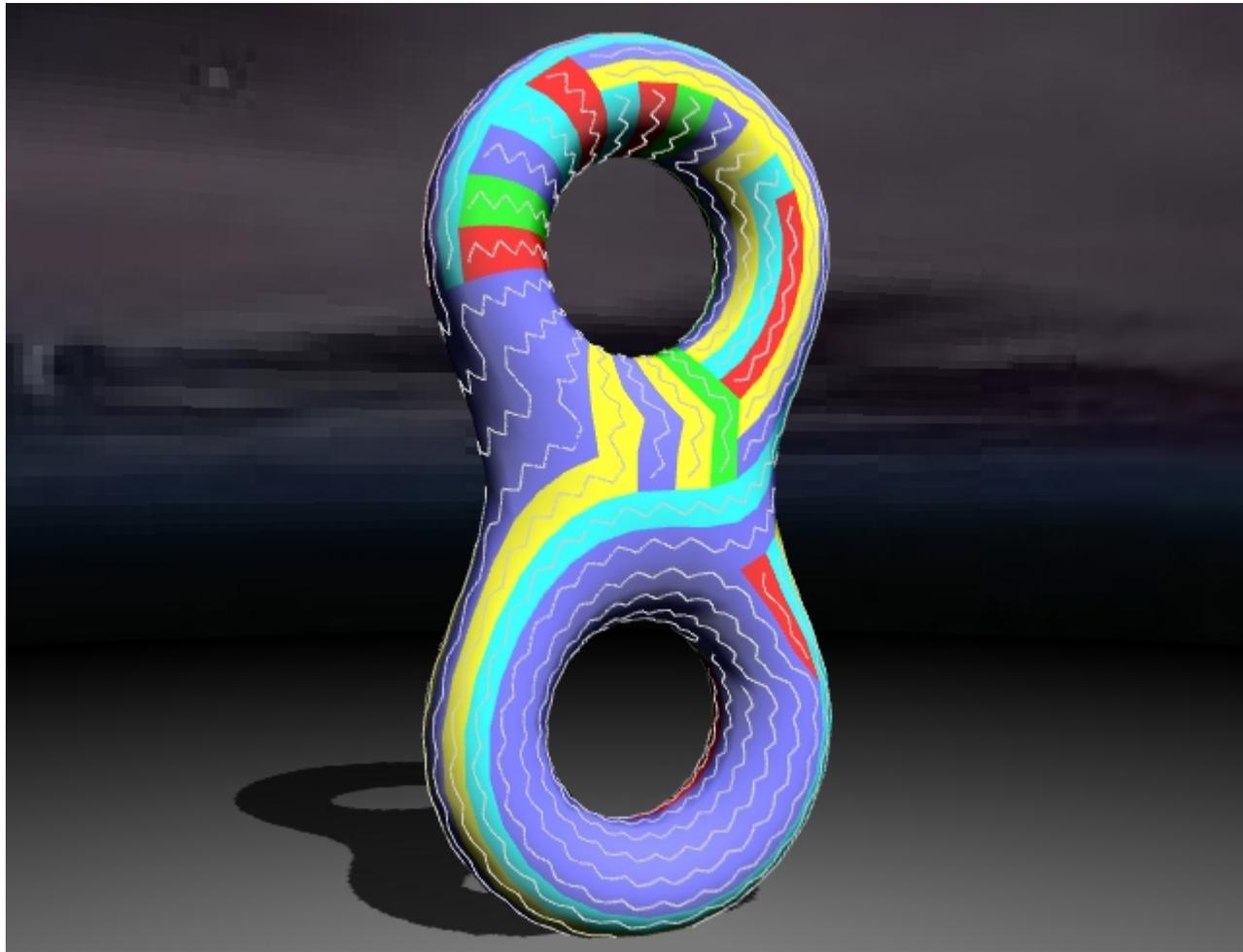
```
class Triangle
{
    HalfEdge halfEdges[3]; // faster access
    uint degree;           // 0, ..., 3
    Triangle *nextInList, // for d-list
              *prevInList;
    Triangle *child[2];   // for spanning tree
}
```

- This minimizes "pointer chasing", makes better use of CPU cache
- This is a mix of face-based and edge-based data structures



# Examples







- Today's graphics cards are so complex and possess so many further features, that it is not clear, whether / how much striping gains us rendering performance!
  - Some GPUs have an integrated index cache (helpful when rendering indexed face sets), so that the pipeline first checks whether a new vertex index is in the cache; if so, then the transformed vertex is retrieved directly from the cache
- In the case where expensive vertex shaders are used, striping surely gains performance
- On mobile graphics chips, striping gains performance for "normal" rendering (as of 2012)
  - Because they have no caches, and much less features
  - But the opinions are mixed ...

